

ADVANCED PLACEMENT PHYSICS B EQUATIONS FOR 2010 and 2011

NEWTONIAN MECHANICS		ELECTRICITY AND MAGNETISM	
$v = v_0 + at$	$a = \text{acceleration}$	$F = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2}$	$A = \text{area}$
$F = \text{force}$	$f = \text{frequency}$	$E = \frac{\mathbf{F}}{q}$	$B = \text{magnetic field}$
$x = x_0 + v_0 t + \frac{1}{2} a t^2$	$h = \text{height}$	$U_E = qV = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r}$	$C = \text{capacitance}$
$J = \text{impulse}$	$K = \text{kinetic energy}$	$E_{avg} = -\frac{V}{d}$	$d = \text{distance}$
$v^2 = v_0^2 + 2a(x - x_0)$	$k = \text{spring constant}$	$V = \frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{r_i}$	$E = \text{electric field}$
$\Sigma \mathbf{F} = \mathbf{F}_{net} = ma$	$\ell = \text{length}$	$C = \frac{Q}{V}$	$\mathcal{E} = \text{emf}$
$F_{fric} \leq \mu N$	$m = \text{mass}$	$U_c = \frac{1}{2} QV = \frac{1}{2} CV^2$	$F = \text{force}$
$a_c = \frac{v^2}{r}$	$N = \text{normal force}$	$I_{avg} = \frac{\Delta Q}{\Delta t}$	$I = \text{current}$
$r = rF \sin \theta$	$P = \text{power}$	$R = \frac{\rho \ell}{A}$	$\ell = \text{length}$
$p = mv$	$p = \text{momentum}$	$V = IR$	$P = \text{power}$
$\mathbf{J} = \mathbf{F}\Delta t = \Delta \mathbf{p}$	$r = \text{radius or distance}$	$P = IV$	$Q = \text{charge}$
$K = \frac{1}{2} mv^2$	$T = \text{period}$	$C_p = \sum_i C_i$	$q = \text{point charge}$
$\Delta U_g = mgh$	$t = \text{time}$	$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$	$R = \text{resistance}$
$W = F\Delta r \cos \theta$	$U = \text{potential energy}$	$R_s = \sum_i R_i$	$r = \text{distance}$
$P_{avg} = \frac{W}{\Delta t}$	$v = \text{velocity or speed}$	$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$	$t = \text{time}$
$P = Fv \cos \theta$	$W = \text{work done on a system}$	$F_B = qvB \sin \theta$	$U = \text{potential (stored) energy}$
$\mathbf{F}_x = -k\mathbf{x}$	$x = \text{position}$	$F_B = BI\ell \sin \theta$	$V = \text{electric potential or}$
$U_s = \frac{1}{2} kx^2$	$\mu = \text{coefficient of friction}$	$B = \frac{\mu_0 I}{2\pi r}$	$\text{potential difference}$
$T_s = 2\pi \sqrt{\frac{m}{k}}$	$\theta = \text{angle}$	$\phi_m = BA \cos \theta$	$v = \text{velocity or speed}$
$T_p = 2\pi \sqrt{\frac{l}{g}}$	$\tau = \text{torque}$	$\mathcal{E}_{avg} = -\frac{\Delta \phi_m}{\Delta t}$	$\rho = \text{resistivity}$
$T = \frac{1}{f}$		$\mathcal{E} = B/v$	$\theta = \text{angle}$
$F_G = -\frac{Gm_1 m_2}{r^2}$			$\phi_m = \text{magnetic flux}$
$U_G = -\frac{Gm_1 m_2}{r}$			